

Using DFT, we started to strain GeS bi-axially ($\pm 5\%$, 1% step) by changing and fixing lattice parameters “a” and “c” simultaneously to their respective new values. A visual representation is shown in Figure 3 (a) and (b).

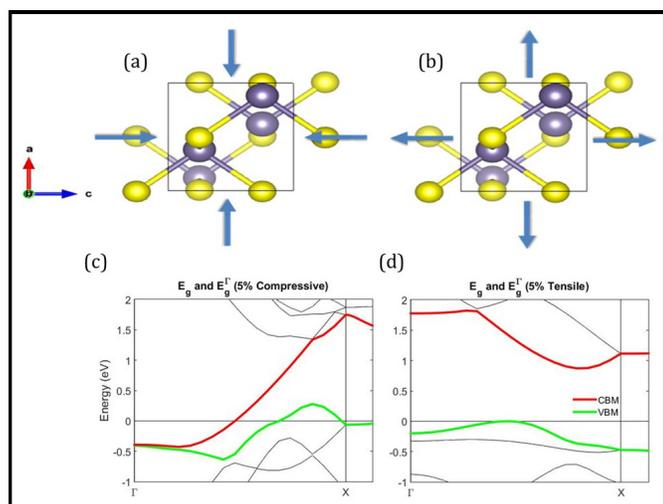


Figure 3: (a) Compressive bi-axial strain. (b) Tensile bi-axial strain. (c) Closing of the gap at 5% compressive strain. (d) $E_g = 0.87$ eV and $E_g^\Gamma = 1.98$ eV at 5% tensile strain.

Results and Conclusions:

We analyzed the fundamental indirect gap of $E_g = 0.78$ eV between valence band maximum (VBM)_s in the $\Gamma \rightarrow X$ direction and CBM at Γ . We also observed a direct gap $E_g^\Gamma = 1.06$ eV at Γ symmetry point. This was due to how close both gaps are in value, and also because a direct gap has less energy loss than an indirect gap. As it is shown in Figure 3 (c), we found that when we applied 5% compressive strain, both E_g and E_g^Γ became zero because the valence and conduction band intersected one another. When it was 5% tensile strained (Figure 3 (d)), both gaps increased, $E_g = 0.87$ eV and $E_g^\Gamma = 1.98$ eV, unfortunately making E_g^Γ too big to remain a competing gap. Also, Figure 4 shows how E_g and E_g^Γ

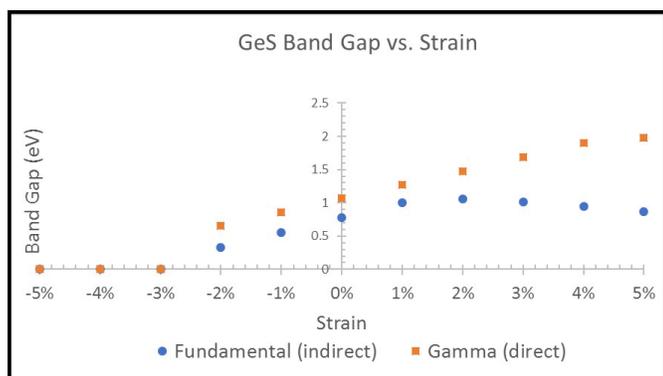


Figure 4: Summary of E_g and E_g^Γ band gap results.

behaved with different strain values. The unstrained result under-estimated the experimental value of 1.74 eV [4]. This indicates some issues in the approximating methods. However, we observed that with tensile strain, CBM changed from Γ point to a position in between the Γ and X path. This opens the possibility of E_g changing from indirect to a direct gap at some point in between.

Future Work:

We will improve the modeling methods to obtain a better match to the experimental gap and decrease the strain step-size to 0.2% around the transition phase between 1% and 2% tensile strain with the hopes of observing a direct gap.

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